

2. Row reduce the system's augmented matrix:

$$\begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ -2 & 4 & 5 & -5 & 3 \\ 3 & -6 & -6 & 8 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & -3 & -1 & 2 \end{bmatrix} \\ \sim \begin{bmatrix} 1 & -2 & -1 & 3 & 0 \\ 0 & 0 & 3 & 1 & 3 \\ 0 & 0 & 0 & 0 & 5 \end{bmatrix}$$

This echelon matrix shows that the system is *inconsistent*, because its rightmost column is a pivot column; the third row corresponds to the equation $0 = 5$. There is no need to perform any more row operations. Note that the presence of the free variables in this problem is irrelevant because the system is inconsistent.

1.3 VECTOR EQUATIONS

Important properties of linear systems can be described with the concept and notation of vectors. This section connects equations involving vectors to ordinary systems of equations. The term *vector* appears in a variety of mathematical and physical contexts, which we will discuss in Chapter 4, “Vector Spaces.” Until then, *vector* will mean an *ordered list of numbers*. This simple idea enables us to get to interesting and important applications as quickly as possible.

Vectors in \mathbb{R}^2

A matrix with only one column is called a **column vector**, or simply a **vector**. Examples of vectors with two entries are

$$\mathbf{u} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} .2 \\ .3 \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$

where w_1 and w_2 are any real numbers. The set of all vectors with two entries is denoted by \mathbb{R}^2 (read “r-two”). The \mathbb{R} stands for the real numbers that appear as entries in the vectors, and the exponent 2 indicates that each vector contains two entries.¹

Two vectors in \mathbb{R}^2 are **equal** if and only if their corresponding entries are equal. Thus $\begin{bmatrix} 4 \\ 7 \end{bmatrix}$ and $\begin{bmatrix} 7 \\ 4 \end{bmatrix}$ are *not* equal, because vectors in \mathbb{R}^2 are *ordered pairs* of real numbers.

Given two vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^2 , their **sum** is the vector $\mathbf{u} + \mathbf{v}$ obtained by adding corresponding entries of \mathbf{u} and \mathbf{v} . For example,

$$\begin{bmatrix} 1 \\ -2 \end{bmatrix} + \begin{bmatrix} 2 \\ 5 \end{bmatrix} = \begin{bmatrix} 1+2 \\ -2+5 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

Given a vector \mathbf{u} and a real number c , the **scalar multiple** of \mathbf{u} by c is the vector $c\mathbf{u}$ obtained by multiplying each entry in \mathbf{u} by c . For instance,

$$\text{if } \mathbf{u} = \begin{bmatrix} 3 \\ -1 \end{bmatrix} \text{ and } c = 5, \quad \text{then } c\mathbf{u} = 5 \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 15 \\ -5 \end{bmatrix}$$

¹Most of the text concerns vectors and matrices that have only real entries. However, all definitions and theorems in Chapters 1–5, and in most of the rest of the text, remain valid if the entries are complex numbers. Complex vectors and matrices arise naturally, for example, in electrical engineering and physics.

The number c in $c\mathbf{u}$ is called a **scalar**; it is written in lightface type to distinguish it from the boldface vector \mathbf{u} .

The operations of scalar multiplication and vector addition can be combined, as in the following example.

EXAMPLE 1 Given $\mathbf{u} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} 2 \\ -5 \end{bmatrix}$, find $4\mathbf{u}$, $(-3)\mathbf{v}$, and $4\mathbf{u} + (-3)\mathbf{v}$.

SOLUTION

$$4\mathbf{u} = \begin{bmatrix} 4 \\ -8 \end{bmatrix}, \quad (-3)\mathbf{v} = \begin{bmatrix} -6 \\ 15 \end{bmatrix}$$

and

$$4\mathbf{u} + (-3)\mathbf{v} = \begin{bmatrix} 4 \\ -8 \end{bmatrix} + \begin{bmatrix} -6 \\ 15 \end{bmatrix} = \begin{bmatrix} -2 \\ 7 \end{bmatrix}$$

Sometimes, for convenience (and also to save space), this text may write a column vector such as $\begin{bmatrix} 3 \\ -1 \end{bmatrix}$ in the form $(3, -1)$. In this case, the parentheses and the comma distinguish the vector $(3, -1)$ from the 1×2 row matrix $\begin{bmatrix} 3 & -1 \end{bmatrix}$, written with brackets and no comma. Thus

$$\begin{bmatrix} 3 \\ -1 \end{bmatrix} \neq \begin{bmatrix} 3 & -1 \end{bmatrix}$$

because the matrices have different shapes, even though they have the same entries.

Geometric Descriptions of \mathbb{R}^2

Consider a rectangular coordinate system in the plane. Because each point in the plane is determined by an ordered pair of numbers, *we can identify a geometric point (a, b) with the column vector $\begin{bmatrix} a \\ b \end{bmatrix}$* . So we may regard \mathbb{R}^2 as the set of all points in the plane. See Fig. 1.

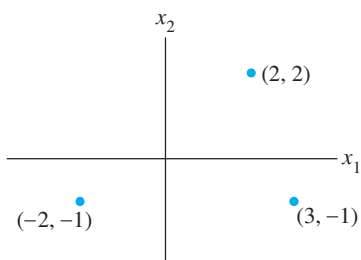


FIGURE 1 Vectors as points.

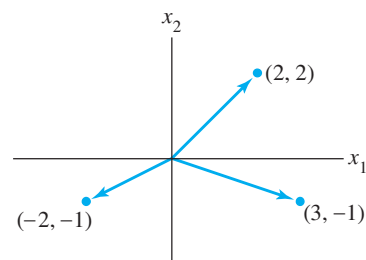


FIGURE 2 Vectors with arrows.

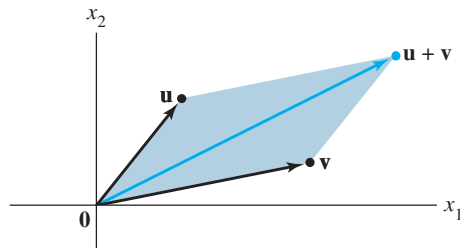
The geometric visualization of a vector such as $\begin{bmatrix} 3 \\ -1 \end{bmatrix}$ is often aided by including an arrow (directed line segment) from the origin $(0, 0)$ to the point $(3, -1)$, as in Fig. 2. In this case, the individual points along the arrow itself have no special significance.²

The sum of two vectors has a useful geometric representation. The following rule can be verified by analytic geometry.

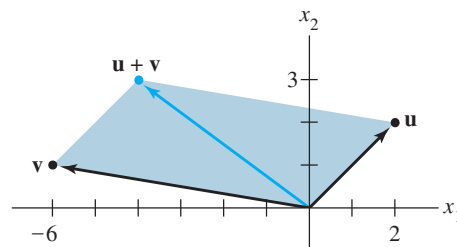
²In physics, arrows can represent forces and usually are free to move about in space. This interpretation of vectors will be discussed in Section 4.1.

Parallelogram Rule for Addition

If \mathbf{u} and \mathbf{v} in \mathbb{R}^2 are represented as points in the plane, then $\mathbf{u} + \mathbf{v}$ corresponds to the fourth vertex of the parallelogram whose other vertices are \mathbf{u} , $\mathbf{0}$, and \mathbf{v} . See Fig. 3.

**FIGURE 3** The parallelogram rule.

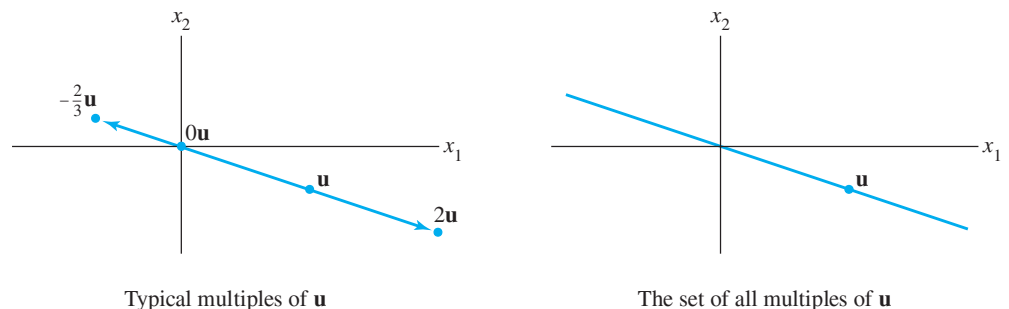
EXAMPLE 2 The vectors $\mathbf{u} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} -6 \\ 1 \end{bmatrix}$, and $\mathbf{u} + \mathbf{v} = \begin{bmatrix} -4 \\ 3 \end{bmatrix}$ are displayed in Fig. 4.

**FIGURE 4**

The next example illustrates the fact that the set of all scalar multiples of one fixed nonzero vector is a line through the origin, $(0, 0)$.

EXAMPLE 3 Let $\mathbf{u} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$. Display the vectors \mathbf{u} , $2\mathbf{u}$, and $-\frac{2}{3}\mathbf{u}$ on a graph.

SOLUTION See Fig. 5, where \mathbf{u} , $2\mathbf{u} = \begin{bmatrix} 6 \\ -2 \end{bmatrix}$, and $-\frac{2}{3}\mathbf{u} = \begin{bmatrix} -2 \\ 2/3 \end{bmatrix}$ are displayed. The arrow for $2\mathbf{u}$ is twice as long as the arrow for \mathbf{u} , and the arrows point in the same direction. The arrow for $-\frac{2}{3}\mathbf{u}$ is two-thirds the length of the arrow for \mathbf{u} , and the arrows point in opposite directions. In general, the length of the arrow for $c\mathbf{u}$ is $|c|$ times the

**FIGURE 5**

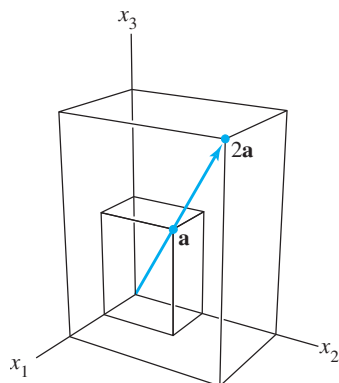


FIGURE 6
Scalar multiples .

length of the arrow for \mathbf{u} . [Recall that the length of the line segment from $(0, 0)$ to (a, b) is $\sqrt{a^2 + b^2}$. We shall discuss this further in Chapter 6.] ■

Vectors in \mathbb{R}^3

Vectors in \mathbb{R}^3 are 3×1 column matrices with three entries. They are represented geometrically by points in a three-dimensional coordinate space, with arrows from the origin sometimes included for visual clarity. The vectors $\mathbf{a} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$ and $2\mathbf{a}$ are displayed

in Fig. 6.

Vectors in \mathbb{R}^n

If n is a positive integer, \mathbb{R}^n (read “r-n”) denotes the collection of all lists (or *ordered n-tuples*) of n real numbers, usually written as $n \times 1$ column matrices, such as

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$$

The vector whose entries are all zero is called the **zero vector** and is denoted by $\mathbf{0}$. (The number of entries in $\mathbf{0}$ will be clear from the context.)

Equality of vectors in \mathbb{R}^n and the operations of scalar multiplication and vector addition in \mathbb{R}^n are defined entry by entry just as in \mathbb{R}^2 . These operations on vectors have the following properties, which can be verified directly from the corresponding properties for real numbers. See Practice Problem 1 and Exercises 33 and 34 at the end of this section.

Algebraic Properties of \mathbb{R}^n

For all $\mathbf{u}, \mathbf{v}, \mathbf{w}$ in \mathbb{R}^n and all scalars c and d :

- | | |
|---|--|
| (i) $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$ | (v) $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$ |
| (ii) $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$ | (vi) $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$ |
| (iii) $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$ | (vii) $c(d\mathbf{u}) = (cd)(\mathbf{u})$ |
| (iv) $\mathbf{u} + (-\mathbf{u}) = -\mathbf{u} + \mathbf{u} = \mathbf{0}$,
where $-\mathbf{u}$ denotes $(-1)\mathbf{u}$ | (viii) $1\mathbf{u} = \mathbf{u}$ |

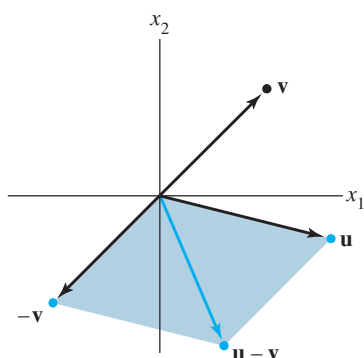


FIGURE 7
Vector subtraction.

For simplicity of notation, a vector such as $\mathbf{u} + (-1)\mathbf{v}$ is often written as $\mathbf{u} - \mathbf{v}$. Figure 7 shows $\mathbf{u} - \mathbf{v}$ as the sum of \mathbf{u} and $-\mathbf{v}$.

Linear Combinations

Given vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ in \mathbb{R}^n and given scalars c_1, c_2, \dots, c_p , the vector \mathbf{y} defined by

$$\mathbf{y} = c_1\mathbf{v}_1 + \cdots + c_p\mathbf{v}_p$$

is called a **linear combination** of $\mathbf{v}_1, \dots, \mathbf{v}_p$ with **weights** c_1, \dots, c_p . Property (ii) above permits us to omit parentheses when forming such a linear combination. The

weights in a linear combination can be any real numbers, including zero. For example, some linear combinations of vectors \mathbf{v}_1 and \mathbf{v}_2 are

$$\sqrt{3}\mathbf{v}_1 + \mathbf{v}_2, \quad \frac{1}{2}\mathbf{v}_1 (= \frac{1}{2}\mathbf{v}_1 + 0\mathbf{v}_2), \quad \text{and} \quad \mathbf{0} (= 0\mathbf{v}_1 + 0\mathbf{v}_2)$$

EXAMPLE 4 Figure 8 identifies selected linear combinations of $\mathbf{v}_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$. (Note that sets of parallel grid lines are drawn through integer multiples of \mathbf{v}_1 and \mathbf{v}_2 .) Estimate the linear combinations of \mathbf{v}_1 and \mathbf{v}_2 that generate the vectors \mathbf{u} and \mathbf{w} .

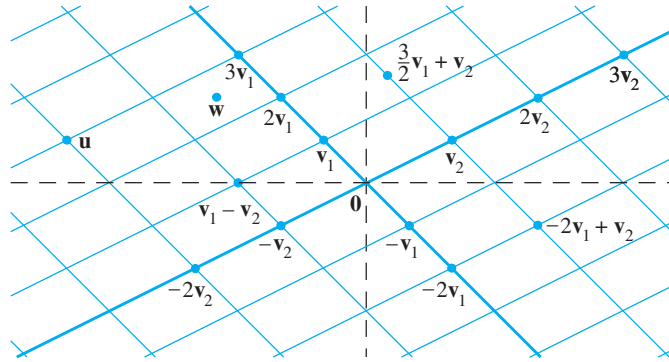


FIGURE 8 Linear combinations of \mathbf{v}_1 and \mathbf{v}_2 .

SOLUTION The parallelogram rule shows that \mathbf{u} is the sum of $3\mathbf{v}_1$ and $-2\mathbf{v}_2$; that is,

$$\mathbf{u} = 3\mathbf{v}_1 - 2\mathbf{v}_2$$

This expression for \mathbf{u} can be interpreted as instructions for traveling from the origin to \mathbf{u} along two straight paths. First, travel 3 units in the \mathbf{v}_1 direction to $3\mathbf{v}_1$, and then travel -2 units in the \mathbf{v}_2 direction (parallel to the line through \mathbf{v}_2 and $\mathbf{0}$). Next, although the vector \mathbf{w} is not on a grid line, \mathbf{w} appears to be about halfway between two pairs of grid lines, at the vertex of a parallelogram determined by $(5/2)\mathbf{v}_1$ and $(-1/2)\mathbf{v}_2$. (See Fig. 9.) Thus a reasonable estimate for \mathbf{w} is

$$\mathbf{w} = \frac{5}{2}\mathbf{v}_1 - \frac{1}{2}\mathbf{v}_2$$

■

The next example connects a problem about linear combinations to the fundamental existence question studied in Sections 1.1 and 1.2.

EXAMPLE 5 Let $\mathbf{a}_1 = \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix}$, $\mathbf{a}_2 = \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix}$, and $\mathbf{b} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$. Determine whether \mathbf{b} can be generated (or written) as a linear combination of \mathbf{a}_1 and \mathbf{a}_2 . That is, determine whether weights x_1 and x_2 exist such that

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 = \mathbf{b} \quad (1)$$

If vector equation (1) has a solution, find it.

SOLUTION Use the definitions of scalar multiplication and vector addition to rewrite the vector equation

$$x_1 \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$$

\uparrow \uparrow \uparrow
 \mathbf{a}_1 \mathbf{a}_2 \mathbf{b}

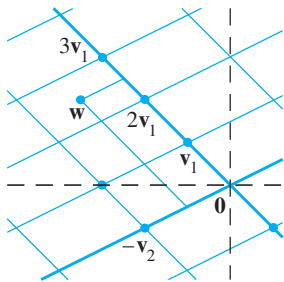


FIGURE 9

which is the same as

$$\begin{bmatrix} x_1 \\ -2x_1 \\ -5x_1 \end{bmatrix} + \begin{bmatrix} 2x_2 \\ 5x_2 \\ 6x_2 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$$

and

$$\begin{bmatrix} x_1 + 2x_2 \\ -2x_1 + 5x_2 \\ -5x_1 + 6x_2 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix} \quad (2)$$

The vectors on the left and right sides of (2) are equal if and only if their corresponding entries are both equal. That is, x_1 and x_2 make the vector equation (1) true if and only if x_1 and x_2 satisfy the system

$$\begin{aligned} x_1 + 2x_2 &= 7 \\ -2x_1 + 5x_2 &= 4 \\ -5x_1 + 6x_2 &= -3 \end{aligned} \quad (3)$$

To solve this system, row reduce the augmented matrix of the system as follows:³

$$\begin{bmatrix} 1 & 2 & 7 \\ -2 & 5 & 4 \\ -5 & 6 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 7 \\ 0 & 9 & 18 \\ 0 & 16 & 32 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 7 \\ 0 & 1 & 2 \\ 0 & 16 & 32 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

The solution of (3) is $x_1 = 3$ and $x_2 = 2$. Hence \mathbf{b} is a linear combination of \mathbf{a}_1 and \mathbf{a}_2 , with weights $x_1 = 3$ and $x_2 = 2$. That is,

$$3 \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} + 2 \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$$

■

Observe in Example 5 that the original vectors \mathbf{a}_1 , \mathbf{a}_2 , and \mathbf{b} are the columns of the augmented matrix that we row reduced:

$$\begin{bmatrix} 1 & 2 & 7 \\ -2 & 5 & 4 \\ -5 & 6 & -3 \end{bmatrix}$$

$\uparrow \quad \uparrow \quad \uparrow$
 $\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{b}$

For brevity, write this matrix in a way that identifies its columns—namely,

$$[\mathbf{a}_1 \quad \mathbf{a}_2 \quad \mathbf{b}] \quad (4)$$

It is clear how to write this augmented matrix immediately from vector equation (1), without going through the intermediate steps of Example 5. Take the vectors in the order in which they appear in (1) and put them into the columns of a matrix as in (4).

The discussion above is easily modified to establish the following fundamental fact.

A vector equation

$$x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2 + \cdots + x_n \mathbf{a}_n = \mathbf{b}$$

has the same solution set as the linear system whose augmented matrix is

$$[\mathbf{a}_1 \quad \mathbf{a}_2 \quad \cdots \quad \mathbf{a}_n \quad \mathbf{b}] \quad (5)$$

In particular, \mathbf{b} can be generated by a linear combination of $\mathbf{a}_1, \dots, \mathbf{a}_n$ if and only if there exists a solution to the linear system corresponding to the matrix (5).

³The symbol \sim between matrices denotes row equivalence (Section 1.2).

One of the key ideas in linear algebra is to study the set of all vectors that can be generated or written as a linear combination of a fixed set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of vectors.

DEFINITION

If $\mathbf{v}_1, \dots, \mathbf{v}_p$ are in \mathbb{R}^n , then the set of all linear combinations of $\mathbf{v}_1, \dots, \mathbf{v}_p$ is denoted by $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ and is called the **subset of \mathbb{R}^n spanned** (or **generated**) **by $\mathbf{v}_1, \dots, \mathbf{v}_p$** . That is, $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is the collection of all vectors that can be written in the form

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_p\mathbf{v}_p$$

with c_1, \dots, c_p scalars.

Asking whether a vector \mathbf{b} is in $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ amounts to asking whether the vector equation

$$x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \cdots + x_p\mathbf{v}_p = \mathbf{b}$$

has a solution, or, equivalently, asking whether the linear system with augmented matrix $[\mathbf{v}_1 \ \cdots \ \mathbf{v}_p \ \mathbf{b}]$ has a solution.

Note that $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ contains every scalar multiple of \mathbf{v}_1 (for example), since $c\mathbf{v}_1 = c\mathbf{v}_1 + 0\mathbf{v}_2 + \cdots + 0\mathbf{v}_p$. In particular, the zero vector must be in $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$.

A Geometric Description of $\text{Span}\{\mathbf{v}\}$ and $\text{Span}\{\mathbf{u}, \mathbf{v}\}$

Let \mathbf{v} be a nonzero vector in \mathbb{R}^3 . Then $\text{Span}\{\mathbf{v}\}$ is the set of all scalar multiples of \mathbf{v} , which is the set of points on the line in \mathbb{R}^3 through \mathbf{v} and $\mathbf{0}$. See Fig. 10.

If \mathbf{u} and \mathbf{v} are nonzero vectors in \mathbb{R}^3 , with \mathbf{v} not a multiple of \mathbf{u} , then $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ is the plane in \mathbb{R}^3 that contains \mathbf{u} , \mathbf{v} , and $\mathbf{0}$. In particular, $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ contains the line in \mathbb{R}^3 through \mathbf{u} and $\mathbf{0}$ and the line through \mathbf{v} and $\mathbf{0}$. See Fig. 11.

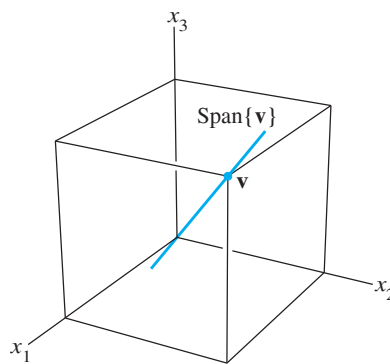


FIGURE 10 $\text{Span}\{\mathbf{v}\}$ as a line through the origin.

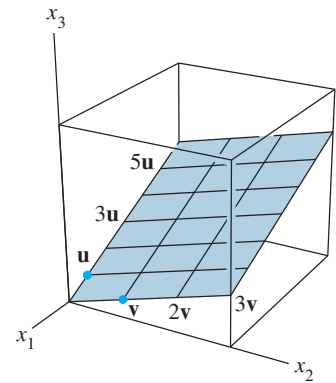


FIGURE 11 $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ as a plane through the origin.

EXAMPLE 6 Let $\mathbf{a}_1 = \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$, $\mathbf{a}_2 = \begin{bmatrix} 5 \\ -13 \\ -3 \end{bmatrix}$, and $\mathbf{b} = \begin{bmatrix} -3 \\ 8 \\ 1 \end{bmatrix}$. Then

$\text{Span}\{\mathbf{a}_1, \mathbf{a}_2\}$ is a plane through the origin in \mathbb{R}^3 . Is \mathbf{b} in that plane?

SOLUTION Does the equation $x_1\mathbf{a}_1 + x_2\mathbf{a}_2 = \mathbf{b}$ have a solution? To answer this, row reduce the augmented matrix $[\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{b}]$:

$$\begin{bmatrix} 1 & 5 & -3 \\ -2 & -13 & 8 \\ 3 & -3 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 5 & -3 \\ 0 & -3 & 2 \\ 0 & -18 & 10 \end{bmatrix} \sim \begin{bmatrix} 1 & 5 & -3 \\ 0 & -3 & 2 \\ 0 & 0 & -2 \end{bmatrix}$$

The third equation is $0 = -2$, which shows that the system has no solution. The vector equation $x_1\mathbf{a}_1 + x_2\mathbf{a}_2 = \mathbf{b}$ has no solution, and so \mathbf{b} is *not* in $\text{Span}\{\mathbf{a}_1, \mathbf{a}_2\}$. ■

Linear Combinations in Applications

The final example shows how scalar multiples and linear combinations can arise when a quantity such as “cost” is broken down into several categories. The basic principle for the example concerns the cost of producing several units of an item when the cost per unit is known:

$$\left\{ \begin{array}{l} \text{number} \\ \text{of units} \end{array} \right\} \cdot \left\{ \begin{array}{l} \text{cost} \\ \text{per unit} \end{array} \right\} = \left\{ \begin{array}{l} \text{total} \\ \text{cost} \end{array} \right\}$$

EXAMPLE 7 A company manufactures two products. For \$1.00 worth of product B, the company spends \$.45 on materials, \$.25 on labor, and \$.15 on overhead. For \$1.00 worth of product C, the company spends \$.40 on materials, \$.30 on labor, and \$.15 on overhead. Let

$$\mathbf{b} = \begin{bmatrix} .45 \\ .25 \\ .15 \end{bmatrix} \quad \text{and} \quad \mathbf{c} = \begin{bmatrix} .40 \\ .30 \\ .15 \end{bmatrix}$$

Then \mathbf{b} and \mathbf{c} represent the “costs per dollar of income” for the two products.

- What economic interpretation can be given to the vector $100\mathbf{b}$?
- Suppose the company wishes to manufacture x_1 dollars worth of product B and x_2 dollars worth of product C. Give a vector that describes the various costs the company will have (for materials, labor, and overhead).

SOLUTION

- Compute

$$100\mathbf{b} = 100 \begin{bmatrix} .45 \\ .25 \\ .15 \end{bmatrix} = \begin{bmatrix} 45 \\ 25 \\ 15 \end{bmatrix}$$

The vector $100\mathbf{b}$ lists the various costs for producing \$100 worth of product B—namely, \$45 for materials, \$25 for labor, and \$15 for overhead.

- The costs of manufacturing x_1 dollars worth of B are given by the vector $x_1\mathbf{b}$, and the costs of manufacturing x_2 dollars worth of C are given by $x_2\mathbf{c}$. Hence the total costs for both products are given by the vector $x_1\mathbf{b} + x_2\mathbf{c}$. ■

PRACTICE PROBLEMS

- Prove that $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$ for any \mathbf{u} and \mathbf{v} in \mathbb{R}^n .
- For what value(s) of h will \mathbf{y} be in $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ if

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 5 \\ -4 \\ -7 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix}, \quad \text{and} \quad \mathbf{y} = \begin{bmatrix} -4 \\ 3 \\ h \end{bmatrix}$$

1.3 EXERCISES

In Exercises 1 and 2, compute $\mathbf{u} + \mathbf{v}$ and $\mathbf{u} - 2\mathbf{v}$.

$$1. \mathbf{u} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} -3 \\ -1 \end{bmatrix} \quad 2. \mathbf{u} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

In Exercises 3 and 4, display the following vectors using arrows on an xy -graph: \mathbf{u} , \mathbf{v} , $-\mathbf{v}$, $-2\mathbf{v}$, $\mathbf{u} + \mathbf{v}$, $\mathbf{u} - \mathbf{v}$, and $\mathbf{u} - 2\mathbf{v}$. Notice that $\mathbf{u} - \mathbf{v}$ is the vertex of a parallelogram whose other vertices are \mathbf{u} , $\mathbf{0}$, and $-\mathbf{v}$.

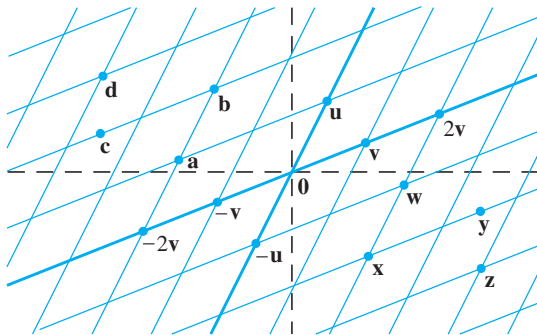
3. \mathbf{u} and \mathbf{v} as in Exercise 1 4. \mathbf{u} and \mathbf{v} as in Exercise 2

In Exercises 5 and 6, write a system of equations that is equivalent to the given vector equation.

$$5. x_1 \begin{bmatrix} 3 \\ -2 \\ 8 \end{bmatrix} + x_2 \begin{bmatrix} 5 \\ 0 \\ -9 \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \\ 8 \end{bmatrix}$$

$$6. x_1 \begin{bmatrix} 3 \\ -2 \end{bmatrix} + x_2 \begin{bmatrix} 7 \\ 3 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Use the accompanying figure to write each vector listed in Exercises 7 and 8 as a linear combination of \mathbf{u} and \mathbf{v} . Is every vector in \mathbb{R}^2 a linear combination of \mathbf{u} and \mathbf{v} ?



7. Vectors \mathbf{a} , \mathbf{b} , \mathbf{c} , and \mathbf{d}

8. Vectors \mathbf{w} , \mathbf{x} , \mathbf{y} , and \mathbf{z}

In Exercises 9 and 10, write a vector equation that is equivalent to the given system of equations.

$$9. \begin{aligned} x_2 + 5x_3 &= 0 \\ 4x_1 + 6x_2 - x_3 &= 0 \\ -x_1 + 3x_2 - 8x_3 &= 0 \end{aligned} \quad 10. \begin{aligned} 3x_1 - 2x_2 + 4x_3 &= 3 \\ -2x_1 - 7x_2 + 5x_3 &= 1 \\ 5x_1 + 4x_2 - 3x_3 &= 2 \end{aligned}$$

In Exercises 11 and 12, determine if \mathbf{b} is a linear combination of \mathbf{a}_1 , \mathbf{a}_2 , and \mathbf{a}_3 .

$$11. \mathbf{a}_1 = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}, \mathbf{a}_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \mathbf{a}_3 = \begin{bmatrix} 5 \\ -6 \\ 8 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix}$$

$$12. \mathbf{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{a}_2 = \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix}, \mathbf{a}_3 = \begin{bmatrix} -6 \\ 7 \\ 5 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 11 \\ -5 \\ 9 \end{bmatrix}$$

In Exercises 13 and 14, determine if \mathbf{b} is a linear combination of the vectors formed from the columns of the matrix A .

$$13. A = \begin{bmatrix} 1 & -4 & 2 \\ 0 & 3 & 5 \\ -2 & 8 & -4 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 3 \\ -7 \\ -3 \end{bmatrix}$$

$$14. A = \begin{bmatrix} 1 & 0 & 5 \\ -2 & 1 & -6 \\ 0 & 2 & 8 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix}$$

15. Let $\mathbf{a}_1 = \begin{bmatrix} 1 \\ 3 \\ -1 \end{bmatrix}$, $\mathbf{a}_2 = \begin{bmatrix} -5 \\ -8 \\ 2 \end{bmatrix}$, and $\mathbf{b} = \begin{bmatrix} 3 \\ -5 \\ h \end{bmatrix}$. For what value(s) of h is \mathbf{b} in the plane spanned by \mathbf{a}_1 and \mathbf{a}_2 ?

16. Let $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} -2 \\ 1 \\ 7 \end{bmatrix}$, and $\mathbf{y} = \begin{bmatrix} h \\ -3 \\ -5 \end{bmatrix}$. For what value(s) of h is \mathbf{y} in the plane generated by \mathbf{v}_1 and \mathbf{v}_2 ?

In Exercises 17 and 18, list five vectors in $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$. For each vector, show the weights on \mathbf{v}_1 and \mathbf{v}_2 used to generate the vector and list the three entries of the vector. Do not make a sketch.

$$17. \mathbf{v}_1 = \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} -4 \\ 0 \\ 1 \end{bmatrix}$$

$$18. \mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} -2 \\ 3 \\ 0 \end{bmatrix}$$

19. Give a geometric description of $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$ for the vectors $\mathbf{v}_1 = \begin{bmatrix} 8 \\ 2 \\ -6 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 12 \\ 3 \\ -9 \end{bmatrix}$.

20. Give a geometric description of $\text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$ for the vectors in Exercise 18.

21. Let $\mathbf{u} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$. Show that $\begin{bmatrix} h \\ k \end{bmatrix}$ is in $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ for all h and k .

22. Construct a 3×3 matrix A , with nonzero entries, and a vector \mathbf{b} in \mathbb{R}^3 such that \mathbf{b} is not in the set spanned by the columns of A .

In Exercises 23 and 24, mark each statement True or False. Justify each answer.

23. a. Another notation for the vector $\begin{bmatrix} -4 \\ 3 \end{bmatrix}$ is $[-4 \ 3]$.
b. The points in the plane corresponding to $\begin{bmatrix} -2 \\ 5 \end{bmatrix}$ and $\begin{bmatrix} -5 \\ 2 \end{bmatrix}$ lie on a line through the origin.
c. An example of a linear combination of vectors \mathbf{v}_1 and \mathbf{v}_2 is the vector $\frac{1}{2}\mathbf{v}_1$.